# Platform for 2018 Summer Project

Jiang Yunwei

## 1 The Structure of the System

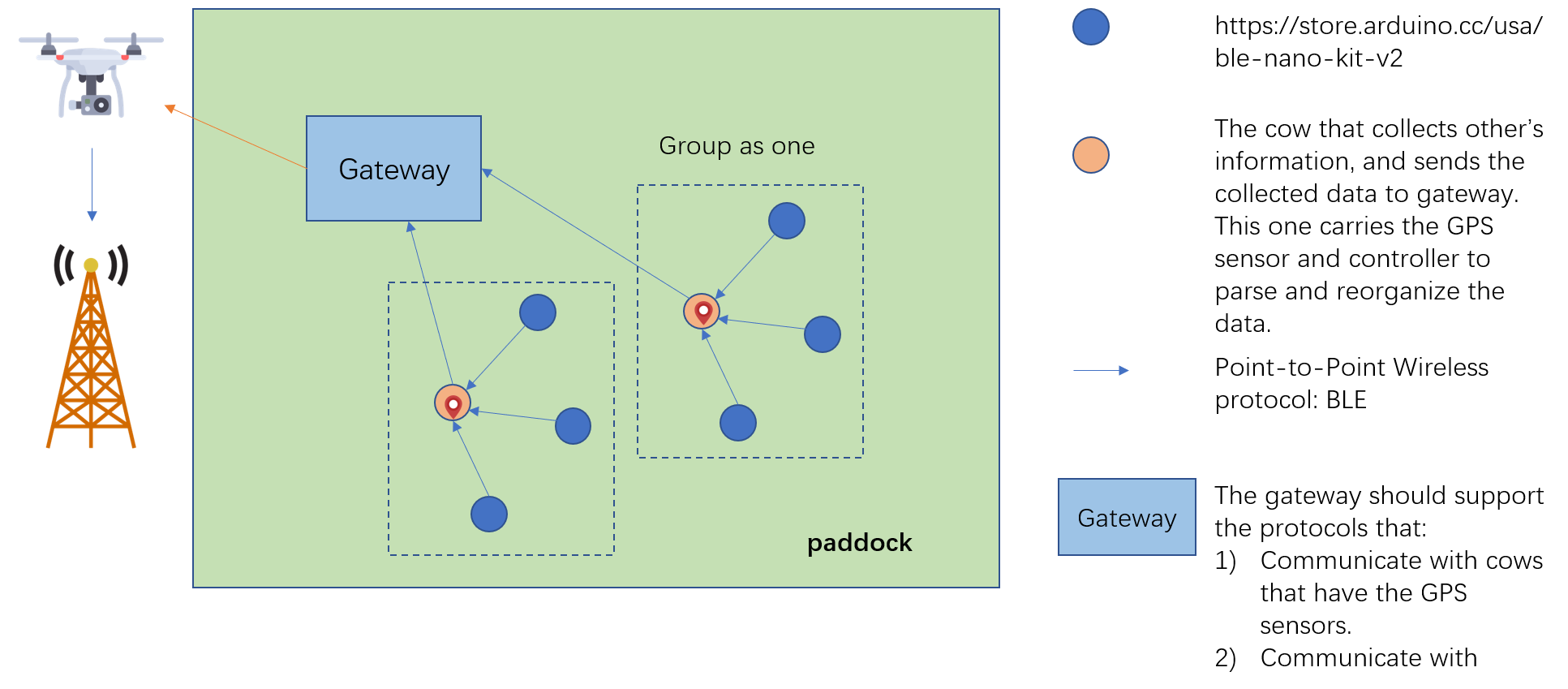


Fig1 Cattle Tracking architecture 1st version

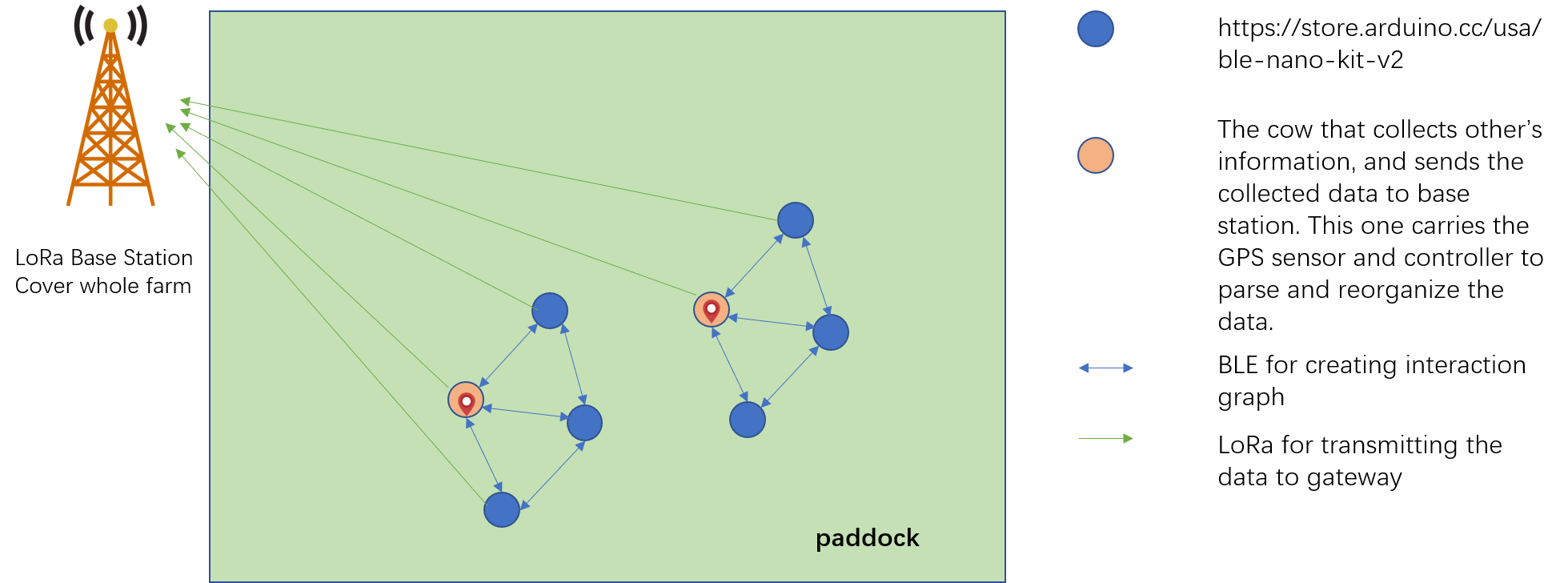


Fig2 Cattle Tracking architecture 2nd version

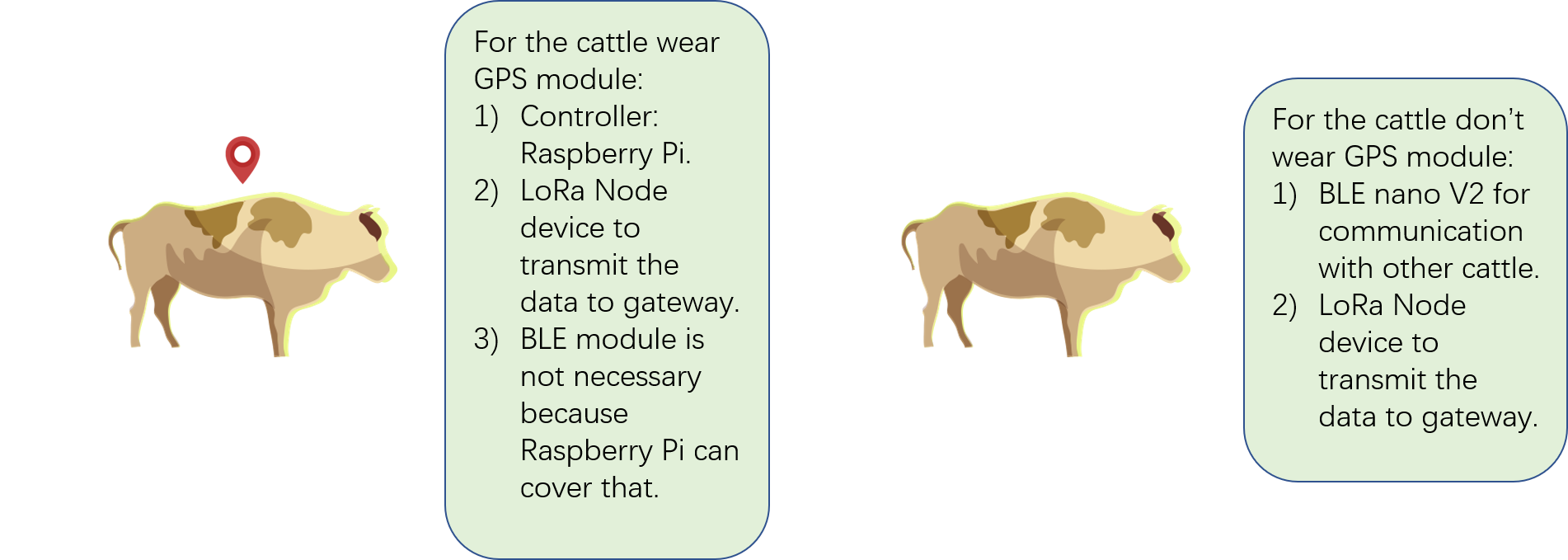


Fig3 Devices worn by cattle version 1

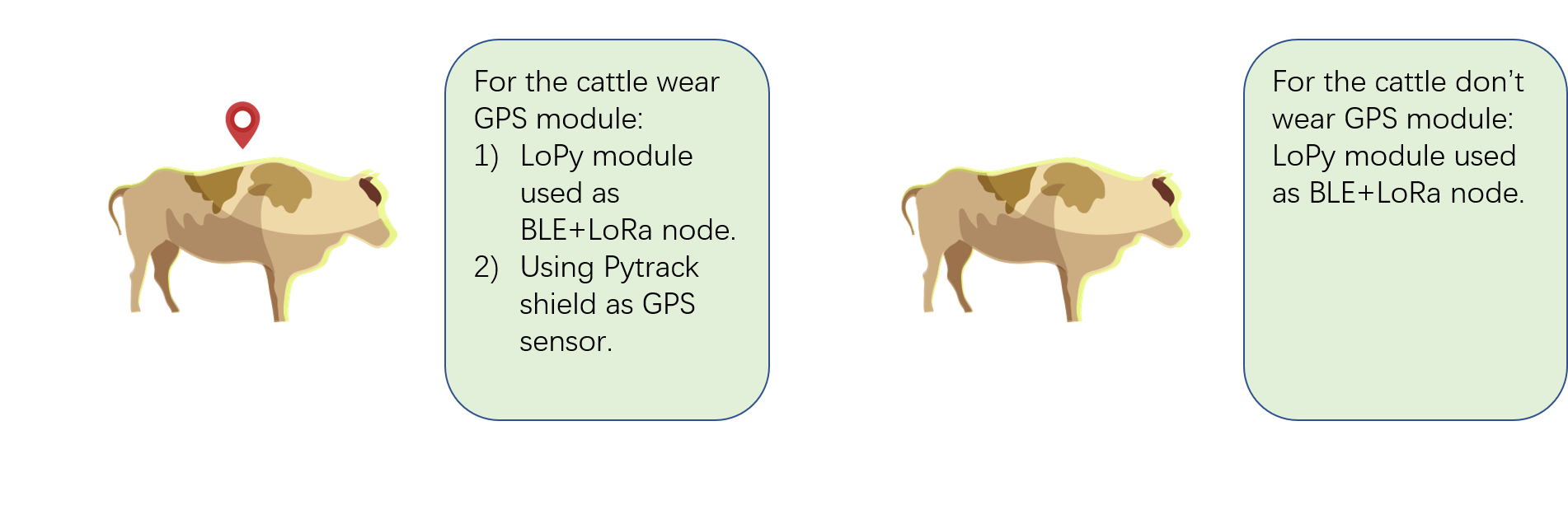


Fig4 Devices worn by cattle version 2

## 2 Device List

### 2.1 Gateway

Works as a bridge between communication devices worn by cattle and the server.

|  |  |  |  |
| --- | --- | --- | --- |
| Device | Parameters | Price | Purchase Link |
|  |  |  |  |
|  |  |  |  |
|  |  |  |  |

### 2.2 BLE device

Communicate between cattle.

|  |  |  |  |
| --- | --- | --- | --- |
| Device | Parameters | Price | Purchase Link |
| **BLE Nano Kit V2**  **(Including a companion board, DAPLink v1.5 board, which is used to load firmware into BLE Nano 2 from a PC)** | 1) nRF52832 BLE SoC  32-bit ARM® Cortex™-M4F CPU with 512kB flash + 64kB RAM  2.4GHz BLE  Bluetooth5  2) Mynewt OS | $32.95 | Purchase link:  <https://store.arduino.cc/usa/ble-nano-kit-v2> |
| **BLE Nano V2** | BLE SoC development board  BLE  1xUART  2xSPI  1xI2C  On board chip antenna | $17.95 | Purchase link:  <https://store.arduino.cc/usa/ble-nano-v2-with-header-soldered> |

### 2.3 GPS sensor

GPS sensors are worn by a certain number of cattle that collect data from other cattle.

|  |  |  |  |
| --- | --- | --- | --- |
| Device | Parameters | Price | Purchase Link |
| **Adafruit Ultimate Breakout** | Satellites: 22 tracking, 66 searching  Patch Antenna Size: 15mm x 15mm x 4mm  Update rate: 1 to 10 Hz  Position Accuracy: < 3 meters  Warm/cold start: 34 seconds  Built in antenna | $39.95 | <https://www.adafruit.com/product/746> |
| **GPS Antenna** | External Active Antenna - 3-5V 28dB 5 Meter SMA | $14.95 | <https://www.adafruit.com/product/960> |
| **SMA to uFL/u.FL/IPX/IPEX RF Adapter Cable** |  | $3.95 | <https://www.adafruit.com/product/851> |

### 2.4 LoRa device

|  |  |  |  |
| --- | --- | --- | --- |
| Device | Parameters | Price | Purchase Link |
| mDot  Long Range LoRa® Modules | The MultiConnect® mDotTM is a secure, CE/FCC/RCM certified, Arm® MbedTM programmable, low-power RF module that provides long-range, low bit rate M2M data connectivity to sensors, industrial equipment and remote appliances. | $31~32(Based on different spectrum) | Introduction:  https://www.multitech.com/brands/multiconnect-mdot |
| MultiConnect® mDotTM Developer Kit | The MultiConnect® mDot™ Developer Kit allows customers to plug in the MultiConnect mDot module and use it for testing, programming and evaluation. | $69.00 | Introduction:  <https://www.multitech.com/brands/micro-mdot-devkit>  Purchase:  <https://www.semiconductorstore.com/cart/pc/viewPrd.asp?idproduct=50707> |
| Arduino Shield |  |  |  |

**Question:** Which Spectrum? mDot supports 868 or 915 MHz.

### 2.5 Controller

Because the data comes from different sources (GPS, BLE), the controller can reorganize and pack the data, then send to gateway.

|  |  |  |  |
| --- | --- | --- | --- |
| Device | Parameters | Price | Purchase Link |
| BeagleBone Black |  |  |  |
| Arduino uno | CPU:ATmega328P 16MHz  Flash:32KB  RAM:2KB SRAM | $22.00 | https://store.arduino.cc/usa/arduino-uno-rev3 |
| Raspberry Pi | ARM Cortex-A53  Bluetooth 4.2/BLE | $35.00 | https://www.adafruit.com/product/3775?src=raspberrypi |

### 2.6 Purchase list

|  |  |  |
| --- | --- | --- |
| Device | Purpose | Price |
| **BLE Nano Kit V2 X1** |  | 1\* $32.95 |
| **BLE Nano V2 X3** |  | 3\* $17.95 |
| **GPS sensor X1** |  | 1\* $39.95 |
| **GPS Antenna X1** |  | 1\* $14.95 |
| **SMA to uFL/u.FL/IPX/IPEX RF Adapter Cable X1** |  | 1\* $3.95 |
| **mDot** |  | 1\* around $32 |
| **mDot Development Kit** |  | 1\* $69 |

### 2.7 1st version device list (2018-06-15)

After searching and comparing for almost two week, now decide to choose LoPy from Pycom as the LoRa node device. LoPy is a BLE+WiFi+LoRa+LoRa nano gateway development board for IoT application.

So now the gateway. To start the work, there are some devices that will used to build up the protype and test:

|  |  |  |
| --- | --- | --- |
| Device | Number | Usage |
| LoPy | 4 | As BLE and LoRa node device, and need to test the performance as a nano gateway. |
| Antenna | 4 | For each LoPy, it needs a external antenna to work normally. |
| Pytrack | 1 | Development shield for LoPy, also contains a GPS receiver. |
| Extension Board 2.0 | 3 | Development shield for LoPy. |
| USB hub | 1 | Power supply for LoPys. |

## 3 Questions

### 3.1 What’s the gateway range?

LoRa base station can cover the farm.

### 3.2 Is there any connection between the cows with the GPS sensors?

Yes

### 3.3 What’s the data transmittd between BLE devices?

For cows without GPS sensor: only ID?

### 3.4 Does all BLE devices store the data?

Probably not. Only transmit the data when comes close to another device.

### 3.5 How often will the data be collected?

### 3.6 Accuracy of the GPS sensor?

Almost all sensor support +/- 3m.

### 3.7 External Power Supply

Battery? Power Bank?

### 3.8 Memory Size

### 3.9 Micro sd card and card reader for flashing the OS?

### 3.10 About the gateway: Buy product or self-integrated?

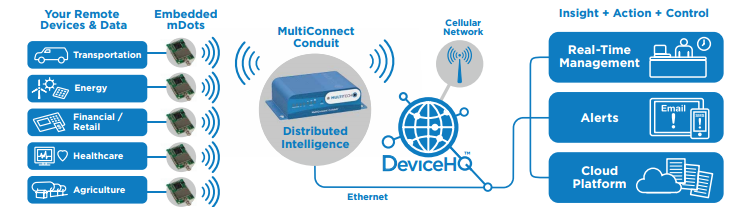
1 There is a gateway also developed by MultiTech: MultiTech® Conduit™ Gateway + mCard around $440

<https://www.multitech.com/brands/multiconnect-conduit>

And rugged outdoor version MultiConnect® Conduit™ IP67 Base Station.

<https://www.multitech.com/brands/multiconnect-conduit-ip67>

The figure below shows the structure of mDot with MultiConnect Conduit gateway:



2 Self-integrated

There are some self-integrated gateway solutions.

Still searching.

### 3.11 ~~How to integrate GPS sensor and mDot to Raspberry pi?~~

1) GPS sensor to Raspberry pi

Input: GPS, output: Rasperry pi

<https://learn.adafruit.com/adafruit-ultimate-gps-on-the-raspberry-pi/introduction>

2) mDot to Raspberry pi

Input: Raspberry pi, output:mDot

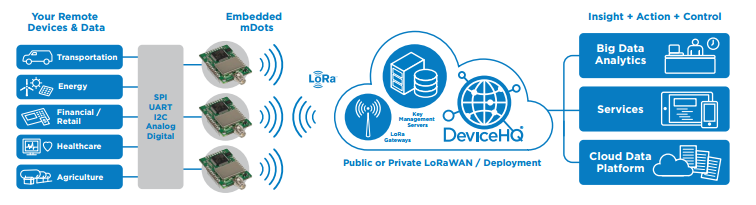
### 3.12 ~~How to integrate BLE nano V2 to mDot?~~

Using BLE nano V2 as input source, and mDot as the output source. So need to find out if nano V2 can connect to mDot?

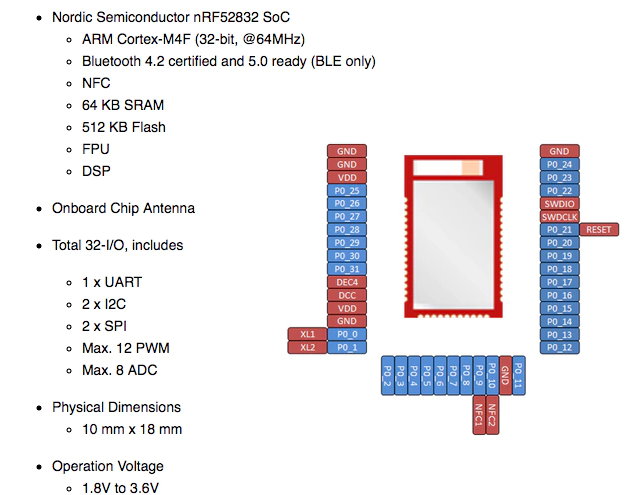
Or still need other shield or controller as a bridge?

As the picture shows below:

mDot can accept data from other device by using SPI, UART, I2C.

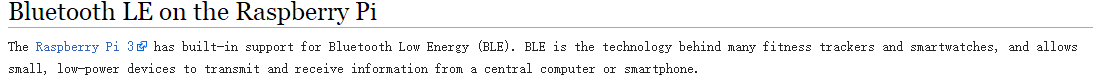


BLE nano V2 supports these:



### 3.13 ~~The communication between BLE nano V2 and Raspberry pi~~

Since



### 3.14 How to test the performance of LoPy both as LoRa node and nano gateway?

## 4 Shopping website

### 4.1 Aruino

### <https://www.arduino.cc/>

### 4.2 Sparkfun

### <https://www.sparkfun.com/>

### 4.3 Adafruit

<https://www.adafruit.com/>

## 5 Development Work Progress

The first three weeks is used for project preparation as paper reading, background knowledge learning, information collecting, device selecting.

### 5.1 Summer Week 4: 06-18~06-22

#### 06-22 Start to work on LoPy

Got all the devices today. First, build up the IDE environment and update firmware for LoPy and Pytrack:

##### 5.1.1 Update Firmware of Pytrack

There is a problem, I can’t get any information from the tools as described in the official doc:

<https://docs.pycom.io/chapter/pytrackpysense/installation/firmware.html>

Except the first time when I followed the instruction and tried to connected Pytrack by using **Zadig** and the information shows as the doc shows, but when I click install driver, it failed and for the rest time Zadig can’t recognize Pytrack anymore:

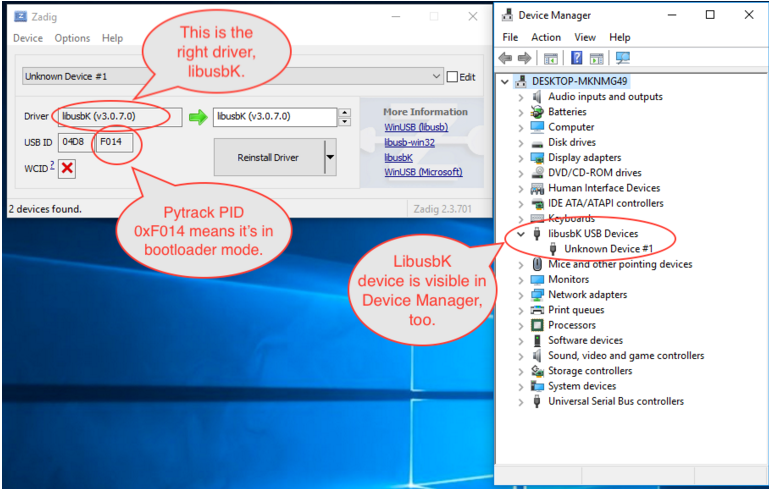


Fig 1 The connection result shown in official doc

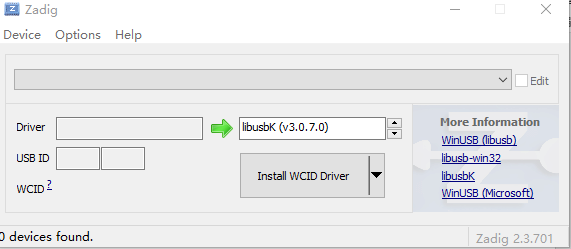
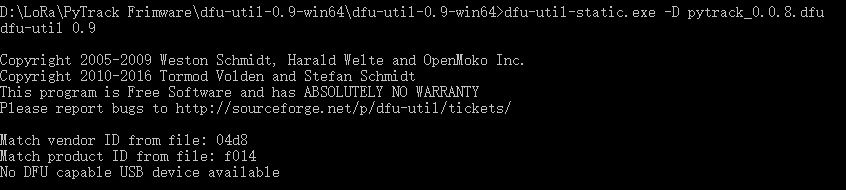
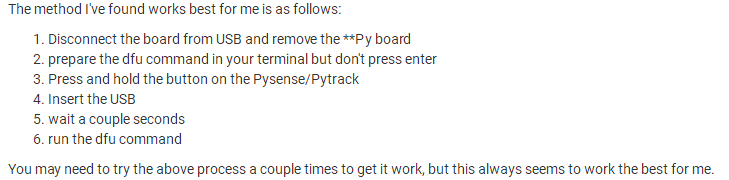


Fig 2

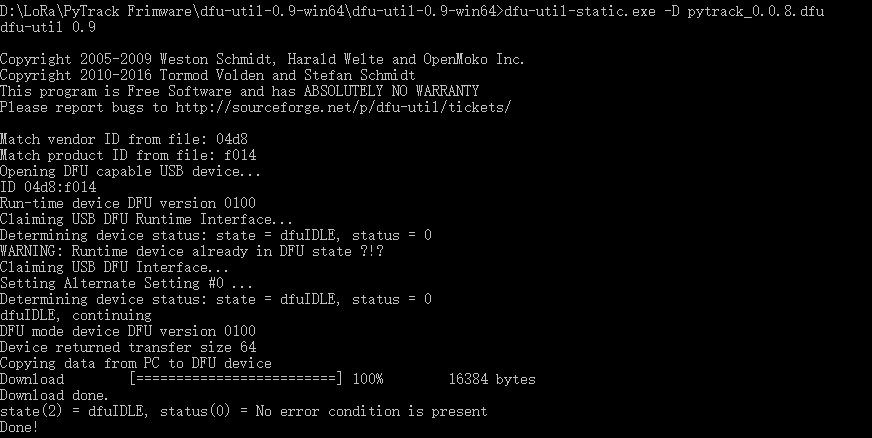
And when using dfu tool to update the firmware, it failed(No DFU capable USB device available).



**But! After followed this instruction from forum, I could still update the firmware for Pytrack:**



After this input the command in console: **dfu-util-static.exe -D pysense\_X.X.X.dfu(change X.X.X to the version of dfu file!)**



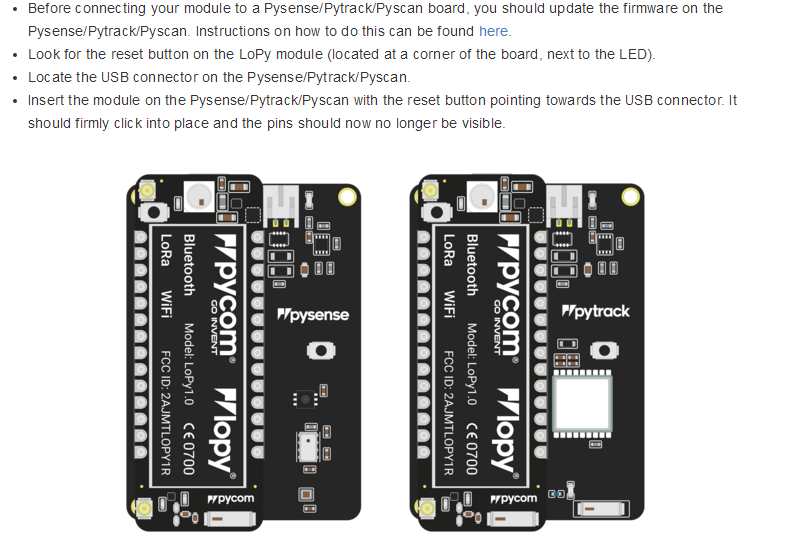
It works!!!

**Need to check this with pycom!**

I guess maybe for Win10 may just automatically installed the

##### 5.1.2 Update firmware for LoPy by Pytrack

Pytrack is easy compared to expansion board 2.0, since it doesn’t need external connection wire:

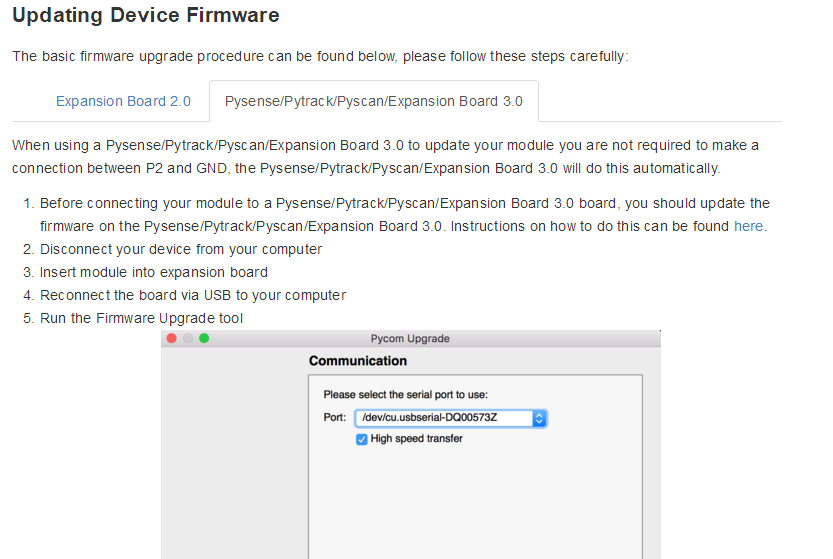


This is from:

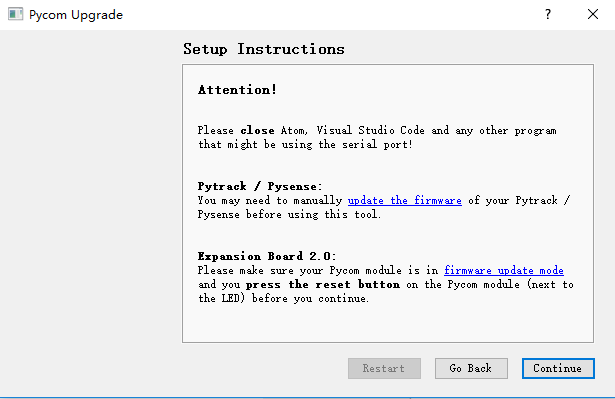
https://docs.pycom.io/chapter/gettingstarted/connection/lopy.html#pic

Then use the Pycom upgrade tool to update device firmware:

https://docs.pycom.io/chapter/gettingstarted/installation/firmwaretool.html#second



In the Pycom Upgrade Tool:



**Note: there are some differences from the official doc!**

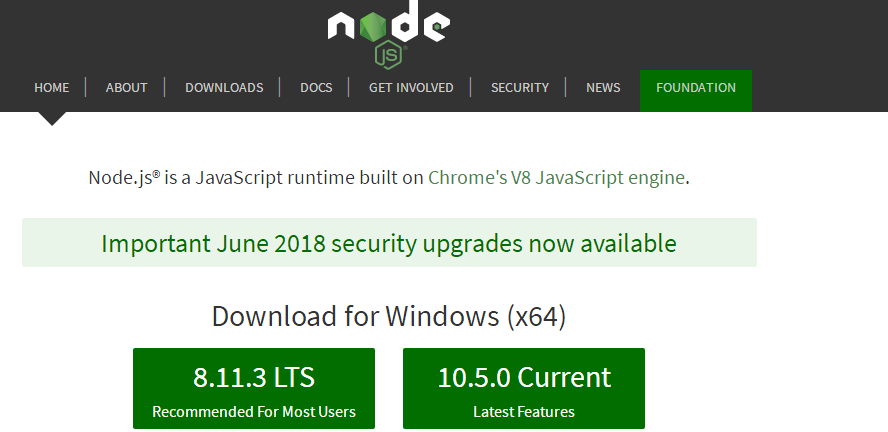
##### 5.1.3 Update firmware for LoPy by Expansion Board 2.0

##### 5.1.4 Setup the IDE environment

Just follow the instruction: https://docs.pycom.io/chapter/pymakr/installation/vscode.html

LoPy use the MicroPython as the programming language.

The recommended IDE is: Visual Studio Code(1.24.1) + NodeJS Latest LTS Version (I installed 8.11.3) + Pymakr Plugin for VS code.

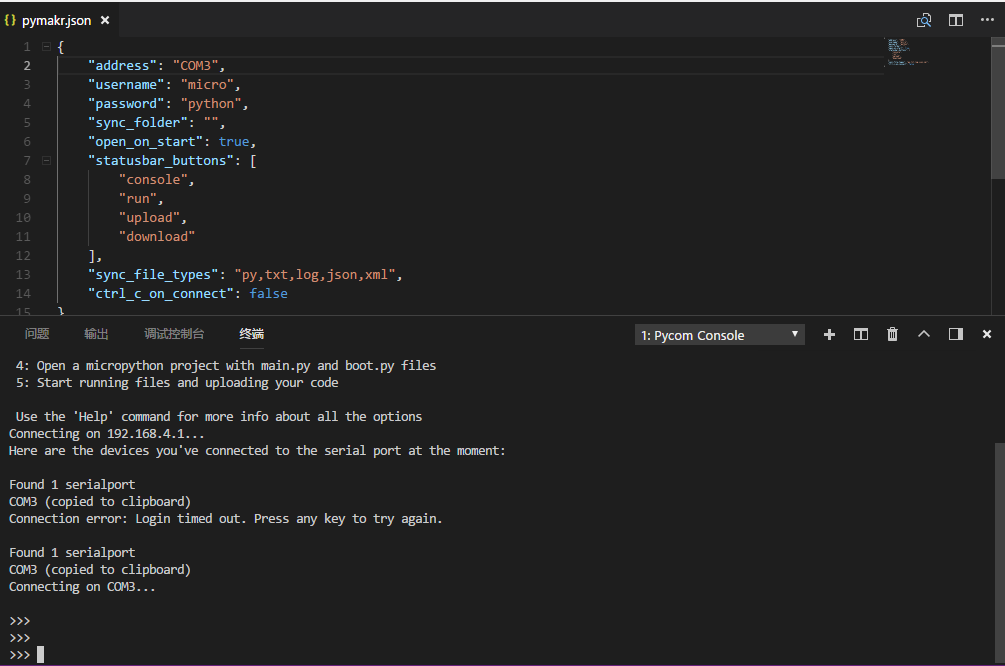


Pymakr is the plugin provided from pycom that could used in vs code.

<https://marketplace.visualstudio.com/items?itemName=pycom.Pymakr>

Just follow the instruction correctly, then will connect LoPy successfully:

**This is connected by serial ports:**



##### 5.1.5 Connect to LoPy by Telnet

##### 5.1.6 Connect to LoPy by FTP

**url**: ftp://192.168.4.1

**username**: micro

**password**: python

##### 5.1.7 First MicroPython example

LoPy has a lot API:

<https://docs.pycom.io/chapter/firmwareapi/>

### 5.2 Summer Week 5: 06-25~06-29

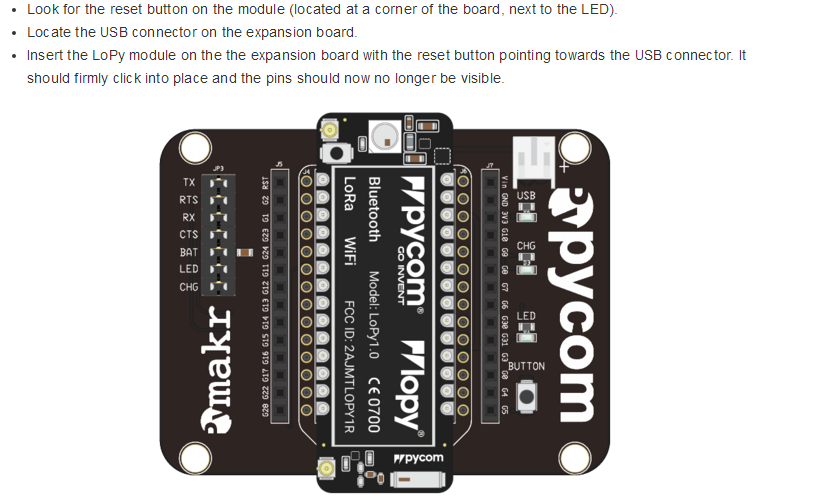
#### 06-25

##### 5.2.1 Update firmware for LoPy by Expansion Board 2.0

Finish firmware update for all LoPy boards today.

About how to insert LoPy to expansion board 2.0:

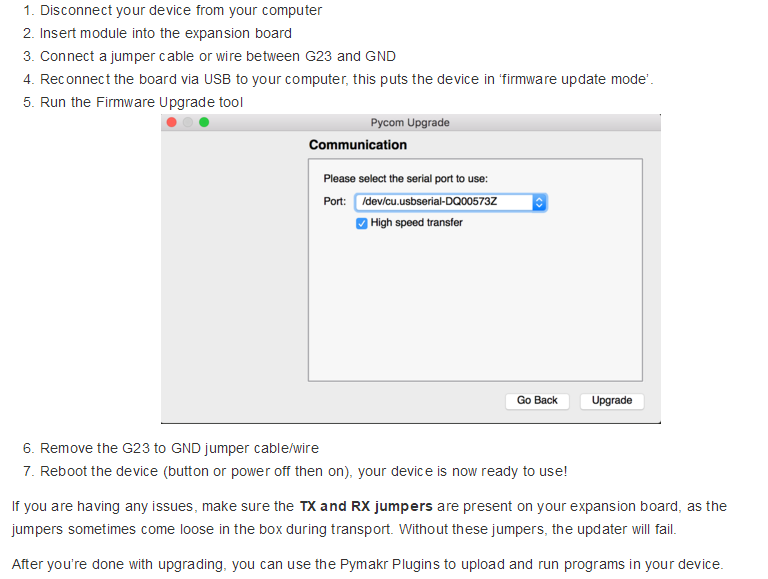
<https://docs.pycom.io/chapter/gettingstarted/connection/lopy.html>



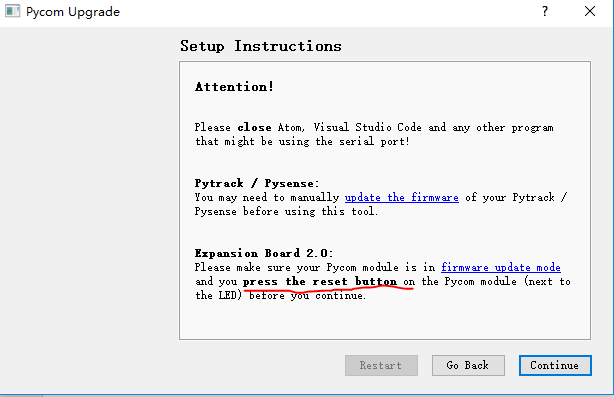
Since don’t need to update the firmware of expansion board 2.0, so just insert Lopy to it. But when update firmware for LoPy, need to use a wire to connect G23 and GND in expansion board.

Follow the link below:

https://docs.pycom.io/chapter/gettingstarted/installation/firmwaretool.html



**Attention! When using the pycom upgrade tool with expansion board 2.0, when this dialog shows, press the reset button before continue!**



##### 5.2.2 LoRa Communication between two LoPys

##### 5.2.3 BLE

##### 5.2.4 GPS example of Pytrack

#### 06-27

Finish Bluetooth communication between two LoPys tests. One as server(which sending the ID all time) and the other one as client(receiving ID and disconnect after get ID).

TO DO list:

1) Still need to know the background knowledge of BLE,GATT

2) There are some other tests need to do:

One server to multiple clients

One client to multiple servers

Multiple servers to multiple clients

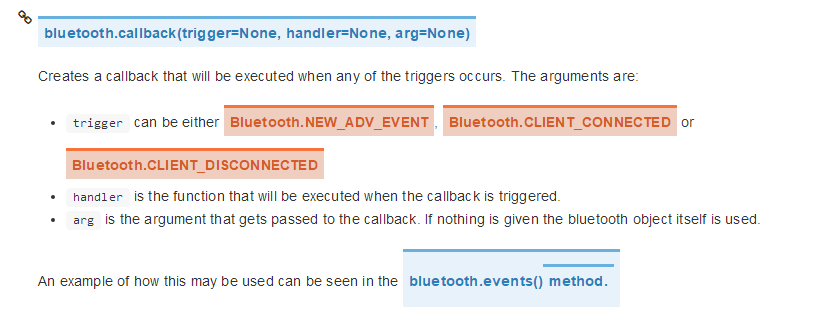
#### 06-28

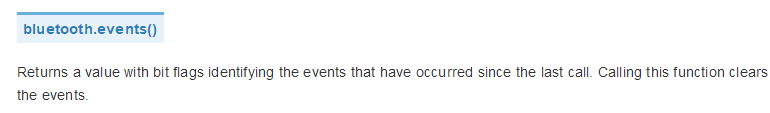
##### 1 I tried to figure out how does BLE work in LoPy:

1) As a server/Central:

Set up an advertisement and send it indefinitely

Add callback function to check the status





The basic idea of using the callback in server is straight forward:

* Bluetooth.events will return the big flags identifying those three events {Bluetooth.CLIENT\_CONNECTED, Bluetooth.CLIENT\_DISCONNECTED, Bluetooth.NEW\_ADV\_EVENT}

To DO list:

1) Check if a LoPy could act as Bluebooth server and client at the same time

2) Multiple thread application test

3) Test BLE and LoRa working at same time

### 5.3 Summer Week 6: 07-02~07-06

#### 07-02

##### 5.3.1 Multiple threads test

1) Test multiple thread running in the LoPy

Exception catch and exit thread

2) BLE and LoRa running in two different threads

These could work!

To do list:

1) When running BLE and LoRa at the same time, need to deal with a shared buffer that for these two protocol.

BLE has both W/R permission.

LoRa only can read.

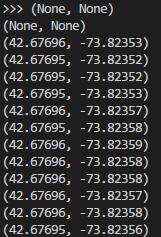
2) Still need to deal with the client connect to one

#### 07-05

**1) Test GPS sensor in Pytrack, it works but something need to be considered first:**

* It need to be used outdoor, I tested in front of UAB, the result shows below:

The first two may failed? Need to consider the timeout before it could return the right coordinate



* If it works correctly, it will return a tuple of (lantitude,longitude) and this tuple can be used to locate cattle.
* For the cattle that don’t wear pytrack so just add (None,None) in the transferred data
* **Make a strategy that deals with the situation when GPS doesn’t work and it could still work as a normal node, and when GPS data recovers just add the data to LoRa package again.**

TO DO list:

1) BLE communication still has problem, I have mailed pycom and hope could get their response soon.

2) LoRa gateway testing which includes three parts:

* Test LoPy wifi connecting to a WiFi network
* Test LoPy to TTN cloud
* Test LoPy as LoRa node send data to LoPy gateway

### 5.4 Summer Week 7: 07-09~07-13

### 5.5 Summer Week 8: 07-16~07-20